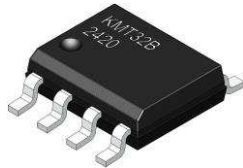




TDFN



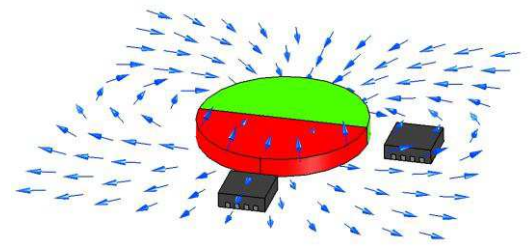
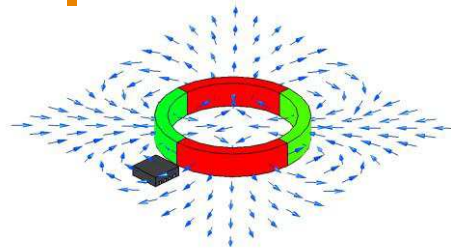
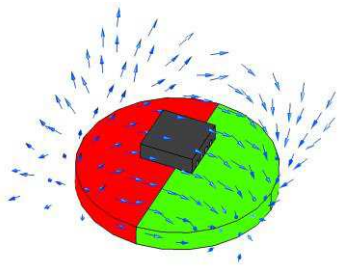
SO8

KMT32B

Magnetic Angle Sensor

- AMR Sensor with 180° period
- high accuracy
- high resolution
- for the use at moderate field strengths
- TDFN- and SO8- package available
- ROHS & REACH compliant

The KMT32B is a magnetic field sensor based on the anisotropic magneto resistance effect, i.e. it is sensing the magnetic field direction independently on the magnetic field strength for applied field strengths $H > 25$ kA/m. The sensor contains two parallel supplied Wheatstone bridges, which enclose a sensitive angle of 45 degrees.



Features

- Contactless angular position, ideal for harsh environments
- Design optimized for linearity
- High accuracy
- Low cost, low power
- Self-diagnosis feature
- Attractive SMD packages
- User has complete control over signal evaluation
- Extended operating temperature range
- REACH & RoHS compliant (lead free)

A rotating magnetic field in the surface parallel to the chip (x-y plane) will therefore deliver two independent sinusoidal output signals, one following a $\cos(2\alpha)$ and the second following a $\sin(2\alpha)$ function, α being the angle between sensor and field direction (see Figure 2).

The KMT32B magnetic field sensor is suited for high precision angle measurement applications at a regular field strength of $H_0 \geq 25$ kA/m (generated for example with magnet 67.044 from Magnetfabrik Bonn at a distance of 5.2 mm at room temperature). With reduced accuracy, the sensor KMT32B may be used with a field strength of $H_0 \geq 14$ kA/m (at room temperature; be aware of the influence of the earth magnetic field!). Most magnets show a decreasing field strength with temperature while the magnetic field direction is unchanged.

Applications

- Absolute and incremental angle measurement
- Automotive (steering angle, torque)
- Robotics
- Camera positioning
- Potentiometer replacement
- Position measurement in medical applications
- Motor motion control

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KMT32B

Characteristic Values

Parameter	Symbol	Condition	Min	Typ	Max	Unit
A. Operating Limits						
Max. supply voltage	$V_{CC,max}$				10	V
Max. current (single bridge)	$I_{CC,max}$				4	mA
Operating temperature	T_{op}		-40		+150	°C
Storage temperature	T_{st}		-40		+150	°C
B. Sensor Specifications (T=25 °C)						
Supply voltage	V_{CC}			5		V
Resistance (single bridge)	R_b		2400	3000	3600	Ω
Output signal amplitude	V_{PEAK}	Condition A, B	9	11	13	mV/V
Offset voltage	V_{OFF}	Condition A, B	-1	0	+1	mV/V
Angular inaccuracy	$\Delta\alpha$	Condition A, B		0.05	0.2	deg
Angular hysteresis	$\Delta\alpha H$	Condition A, B			0.1	deg
C. Sensor Specifications						
TC of amplitude	TCSV	Condition A, C		-0.35		%/K
TC of resistance	TCBR	Condition A, C		+0.35		%/K
TC of offset	TCVoff	Condition A, C	-4	0	+4	$\mu V/V/K$

Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.

Measurement Condition

Parameter	Symbol	Unit	Condition
Condition A: Set Up Conditions			
Ambient temperature	T	°C	T = 25 °C (unless otherwise noted)
Supply voltage	V_{CC}	V	$V_{CC} = 5\text{ V}$
Applied magnetic field	H	kA/m	H = 25 kA/m

Condition B: Sensor Specifications (360° turn , $V_{Omax}>0$, $V_{Omin}<0$)			
Output signal amplitude	V_{PEAK}	mV/V	$V_{PEAK} = (V_{Omax} - V_{Omin})/2/V_{CC}$
Offset voltage	V_{OFF}	mV/V	$V_{OFF} = (V_{Omax} + V_{Omin})/2/V_{CC}$
Angular inaccuracy	$\Delta\alpha$	deg	$\Delta\alpha = MAX \alpha_0 - \alpha $; max. angular difference between actual field angle α_0 and measured angle α due to deviations from ideal sinusoidal characteristics, calculated from the third and fifth harmonics of the Fourier spectrum; offset voltage error contributions not included
Angular hysteresis	$\Delta\alpha H$	deg	$\Delta\alpha H = \alpha_{left\ turn} - \alpha_{right\ turn} $ angular difference between left and right turn

Measurement Condition

Parameter	Symbol	Unit	Condition
Condition C: Sensor Specifications (-25°C, +125°C)			
Ambient temperatures	T	°C	T ₁ = -25 °C, T ₀ = +25 °C, T ₂ = +125 °C
TC of amplitude	TCSV	%/K	$TCV = \frac{1}{(T_2 - T_1)} \cdot \frac{\frac{\Delta Vn}{Vcc}(T_2) - \frac{\Delta Vn}{Vcc}(T_1)}{\frac{\Delta Vn}{Vcc}(T_1)} \cdot 100\%$
TC of resistance	TCBR	%/K	$TCR = \frac{1}{(T_2 - T_1)} \cdot \frac{R(T_2) - R(T_1)}{R(T_1)} \cdot 100\%$
TC of offset	TCVoff	(μV/V)/K	$TCVoff = \frac{Voff(T_2) - Voff(T_1)}{(T_2 - T_1)}$

Block Diagram

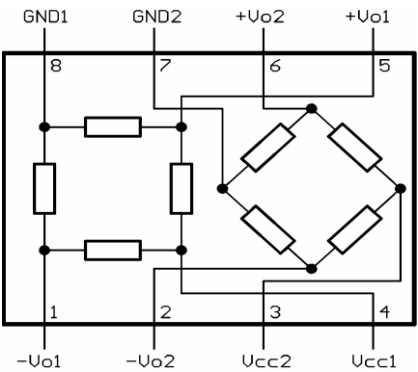


Figure 1: Circuit Diagram for the KMT32B in the SO8-Package

Typical Performance Curves

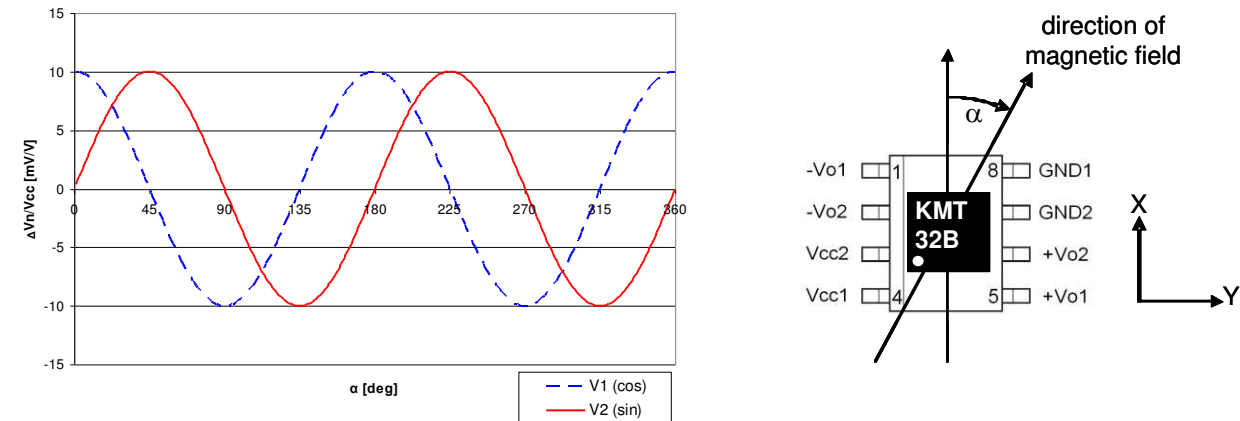


Figure 2: Characteristic curves for KMT32B (SO8, TDFN)

KMT32B

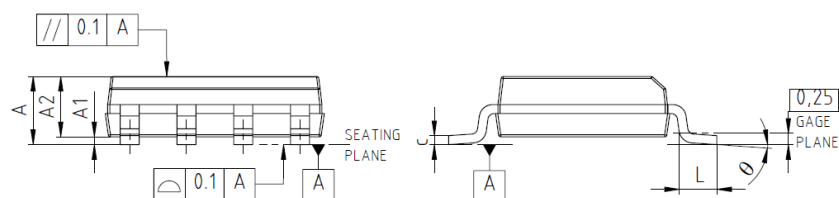
Magnetic Angle Sensor

Pin Assignment (SO8, TDFN)

Pin (SO8)	Pin (TDFN)	Symbol	Function
1	7	$-V_{o1}$	negative output bridge 1
2	8	$-V_{o2}$	negative output bridge 2
3	1	V_{cc2}	positive supply voltage bridge 2
4	2	V_{cc1}	positive supply voltage bridge 1
5	3	$+V_{o1}$	positive output bridge 1
6	4	$+V_{o2}$	positive output bridge 2
7	5	GND_2	negative supply voltage bridge 2
8	6	GND_1	negative supply voltage bridge 1

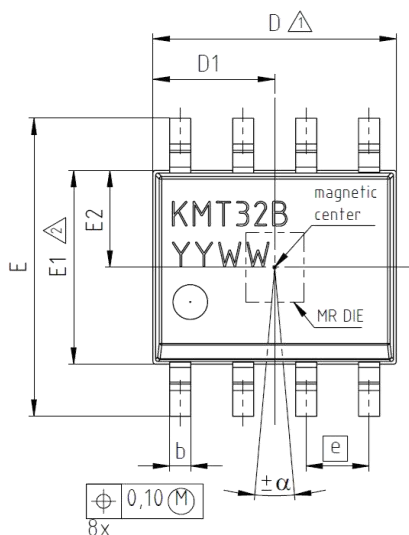
Packages

SO8



MARKING
KMT32B

Manufacturing date: YYWW
YY: year
WW: week



DIMENSION MM			
REF	MIN.	NOM.	MAX.
A	1.35	-	1.75
A1	0.10	-	0.25
A2	1.25	-	1.50
b	0.35	-	0.50
c	0.17	-	0.24
D	4.80	-	5.00
D1	-	2.45	-
E	5.80	-	6.20
E1	3.80	-	4.00
E2	-	1.95	-
e	-	1.27	-
L	0.40	-	1.27
θ	0°	-	8°
α	-5°	0°	+5°

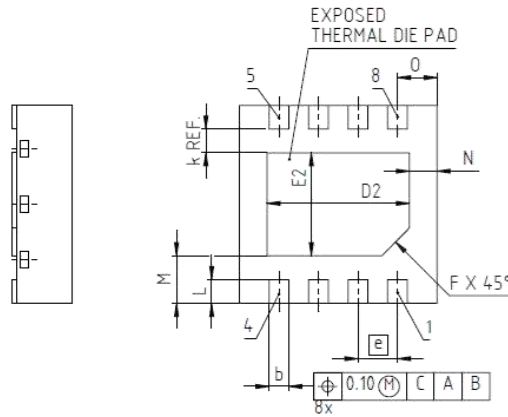
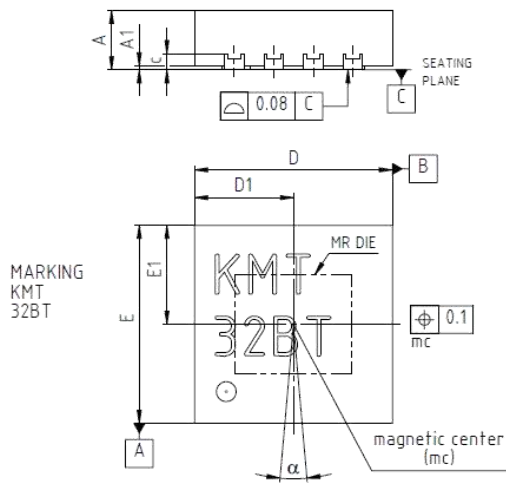
Quality information

This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q101 - Failure mechanism-based stress test for discrete semiconductor and is suitable for use in automotive applications.

KMT32B

Magnetic Angle Sensor

TDFN 2.5 x 2.5 x 0.75 mm³



DIMENSION MM			
REF	MIN.	NOM.	MAX.
A	0.70	0.75	0.80
A1	-	-	0.05
b	0.20	0.25	0.30
c	-	0.20	-
D	2.45	2.50	2.55
D1	-	1.25	-
D2	1.79	1.80	1.81
E	2.45	2.50	2.55
E1	-	1.25	-
E2	1.29	1.30	1.31
e	-	0.50	-
F	-	0.35	-
k	-	0.30	-
L	0.25	0.30	0.35
M	-	0.60	-
N	-	0.35	-
O	-	0.50	-
α	-5°	0°	5°

Quality information

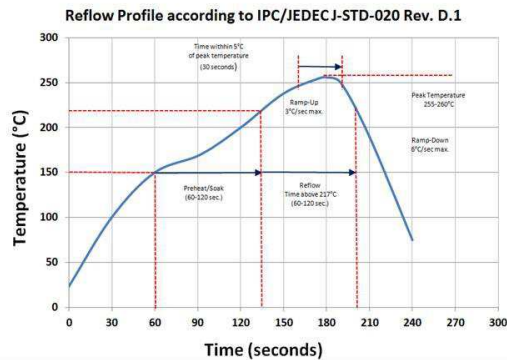
This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q101 - Failure mechanism-based stress test for discrete semiconductor.

Solder Profile

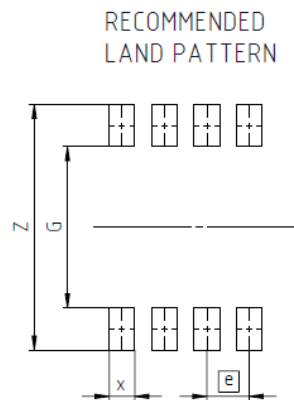
KMT32BT/G-MRCO-016

Package: 8L TDFN 2.5 x 2.5

Solder Profile



Recommended Land Pattern



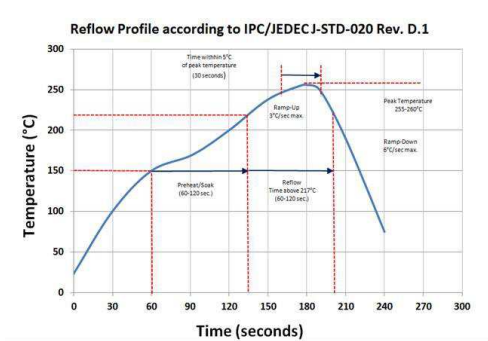
DIMENSION MM			
REF	MIN.	NOM.	MAX.
X	-	0.30	-
G	1.90	-	-
Z	-	-	2.90
e	-	0.50	-

Moisture Sensitivity Level for KMT32BT: MSL1 @ 260°C

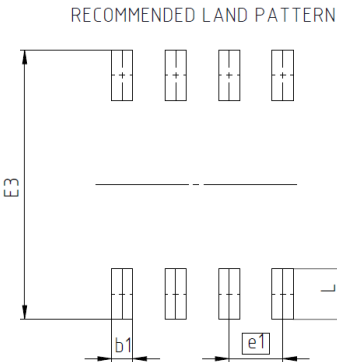
KMT32B/G-MRCO-015

Package: SO8

Solder Profile



Recommended Land Pattern



	Millimeter		
DIM	min.	typ.	max.
b1	-	0.50	-
E3	-	6.40	-
e1	-	1.27	-
L	-	1.20	-

Moisture Sensitivity Level for KMT32B: MSL1 @ 260°C

Tape and Reel Packaging Information

Description	Part#	Reel size	Units/reel	Pin 1 orientation	Note
KMT32B/TD	G-MRCO-016	7"	3,000	Top-right of sprocket hole side	
KMT32B/SO	G-MRCO-016	13"	2,500	Top-left of sprocket hole side	

KMT32B

Magnetic Angle Sensor

Ordering Information

Description	Part Number
KMT32B 8L SOIC ROHS	G-MRCO-015
KMT32BT TDFN ROHS	G-MRCO-016

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