

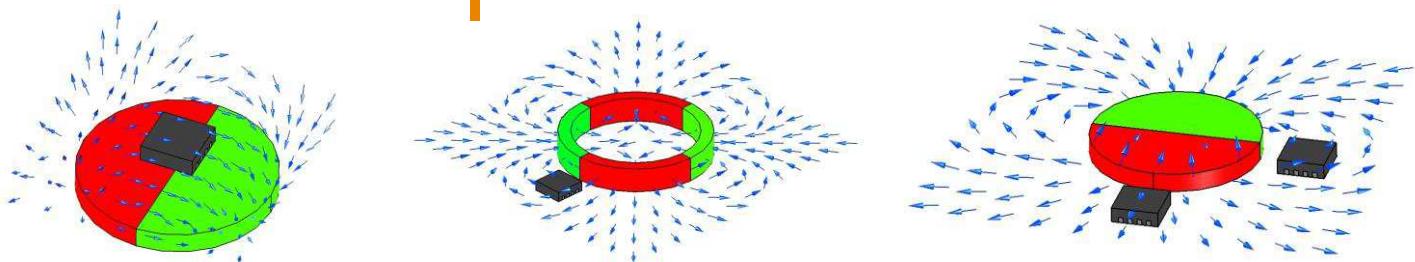


## KMT32B

### Magnetic Angle Sensor

- AMR Sensor with 180° period
- high accuracy
- high resolution
- for the use at moderate field strengths
- TDFN- and SO8- package available
- ROHS & REACH compliant

The KMT32B is a magnetic field sensor based on the anisotropic magneto resistance effect, i.e. it is sensing the magnetic field direction independently on the magnetic field strength for applied field strengths  $H > 25$  kA/m. The sensor contains two parallel supplied Wheatstone bridges, which enclose a sensitive angle of 45 degrees.



### Features

- Contactless angular position, ideal for harsh environments
- Design optimized for linearity
- High accuracy
- Low cost, low power
- Self-diagnosis feature
- Attractive SMD packages
- User has complete control over signal evaluation
- Extended operating temperature range
- REACH & RoHS compliant (lead free)

A rotating magnetic field in the surface parallel to the chip (x-y plane) will therefore deliver two independent sinusoidal output signals, one following a  $\cos(2\alpha)$  and the second following a  $\sin(2\alpha)$  function,  $\alpha$  being the angle between sensor and field direction (see Figure 2).

The KMT32B magnetic field sensor is suited for high precision angle measurement applications at a regular field strength of  $H_0 \geq 25$  kA/m (generated for example with magnet 67.044 from Magnetfabrik Bonn at a distance of 5.2 mm at room temperature). With reduced accuracy, the sensor KMT32B may be used with a field strength of  $H_0 \geq 14$  kA/m (at room temperature; be aware of the influence of the earth magnetic field!). Most magnets show a decreasing field strength with temperature while the magnetic field direction is unchanged.

### Applications

- Absolute and incremental angle measurement
- Automotive (steering angle, torque)
- Robotics
- Camera positioning
- Potentiometer replacement
- Position measurement in medical applications
- Motor motion control

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## KMT32B

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## KMT32B

### Characteristic Values

Parameter	Symbol	Condition	Min	Typ	Max	Unit
<b>A. Operating Limits</b>						
Max. supply voltage	V <sub>CC,max</sub>				<b>10</b>	V
Max. current (single bridge)	I <sub>CC,max</sub>				<b>4</b>	mA
Operating temperature	T <sub>op</sub>		<b>-40</b>		<b>+150</b>	°C
Storage temperature	T <sub>st</sub>		<b>-40</b>		<b>+150</b>	°C
<b>B. Sensor Specifications (T=25 °C)</b>						
Supply voltage	V <sub>CC</sub>			<b>5</b>		V
Resistance (single bridge)	R <sub>b</sub>		<b>2400</b>	<b>3000</b>	<b>3600</b>	Ω
Output signal amplitude	V <sub>PEAK</sub>	Condition A, B	<b>9</b>	<b>11</b>	<b>13</b>	mV/V
Offset voltage	V <sub>OFF</sub>	Condition A, B	<b>-1</b>	<b>0</b>	<b>+1</b>	mV/V
Angular inaccuracy	Δα	Condition A, B		<b>0.05</b>	<b>0.2</b>	deg
Angular hysteresis	ΔαH	Condition A, B			<b>0.1</b>	deg
<b>C. Sensor Specifications</b>						
TC of amplitude	T <sub>CSV</sub>	Condition A, C		<b>-0.35</b>		%/K
TC of resistance	T <sub>CBR</sub>	Condition A, C		<b>+0.35</b>		%/K
TC of offset	T <sub>CVoff</sub>	Condition A, C	<b>-4</b>	<b>0</b>	<b>+4</b>	μV/V/K

Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.

### Measurement Condition

Parameter	Symbol	Unit	Condition
<b>Condition A: Set Up Conditions</b>			
Ambient temperature	T	°C	T = 25 °C (unless otherwise noted)
Supply voltage	V <sub>CC</sub>	V	V <sub>CC</sub> = 5 V
Applied magnetic field	H	kA/m	H = 25 kA/m

<b>Condition B: Sensor Specifications (360° turn, V<sub>0,max</sub>&gt;0, V<sub>0,min</sub>&lt;0)</b>			
Output signal amplitude	V <sub>PEAK</sub>	mV/V	V <sub>PEAK</sub> = (V <sub>0,max</sub> - V <sub>0,min</sub> )/2/V <sub>CC</sub>
Offset voltage	V <sub>OFF</sub>	mV/V	V <sub>OFF</sub> = (V <sub>0,max</sub> + V <sub>0,min</sub> )/2/V <sub>CC</sub>
Angular inaccuracy	Δα	deg	Δα = MAX/ α <sub>0</sub> -α ; max. angular difference between actual field angle α <sub>0</sub> and measured angle α due to deviations from ideal sinusoidal characteristics, calculated from the third and fifth harmonics of the Fourier spectrum; offset voltage error contributions not included
Angular hysteresis	ΔαH	deg	ΔαH =  α <sub>left turn</sub> - α <sub>right turn</sub>  /angular difference between left and right turn

## Measurement Condition

Parameter	Symbol	Unit	Condition
<b>Condition C: Sensor Specifications (-25°C, +125°C)</b>			
Ambient temperatures	T	°C	$T_1 = -25 \text{ }^{\circ}\text{C}$ , $T_0 = +25 \text{ }^{\circ}\text{C}$ , $T_2 = +125 \text{ }^{\circ}\text{C}$
TC of amplitude	TCSV	%/K	$TCV = \frac{1}{(T_2 - T_1)} \cdot \frac{\frac{\Delta Vn}{Vcc}(T_2) - \frac{\Delta Vn}{Vcc}(T_1)}{\frac{\Delta Vn}{Vcc}(T_1)} \cdot 100\%$
TC of resistance	TCBR	%/K	$TCR = \frac{1}{(T_2 - T_1)} \cdot \frac{R(T_2) - R(T_1)}{R(T_1)} \cdot 100\%$
TC of offset	TCVoff	( $\mu$ V/V)/K	$TCVoff = \frac{Voff(T_2) - Voff(T_1)}{(T_2 - T_1)}$

## Block Diagram

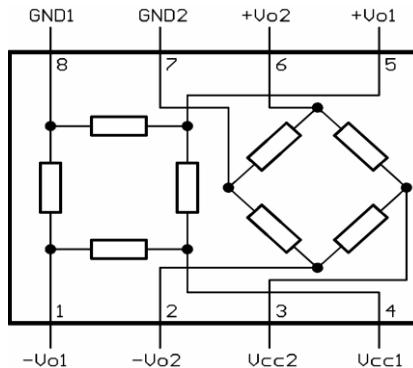


Figure 1: Circuit Diagram for the KMT32B in the SO8-Package

## Typical Performance Curves

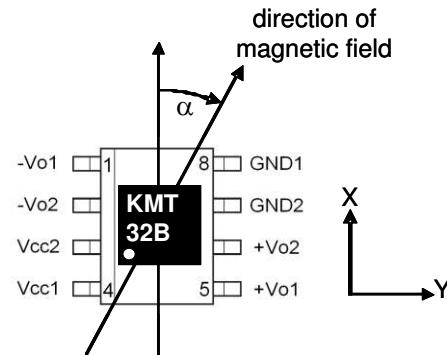
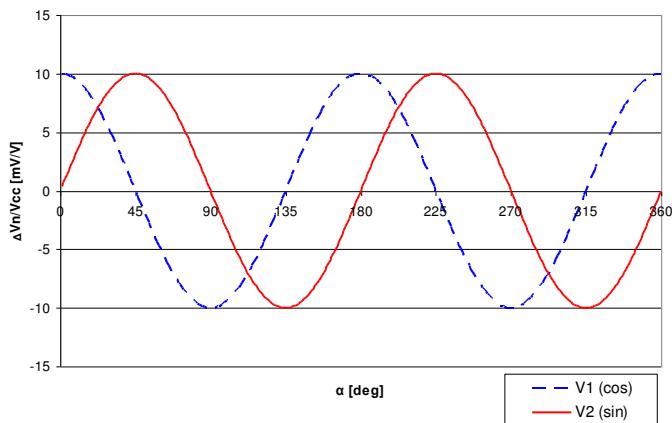


Figure 2: Characteristic curves for KMT32B (SO8, TDFN)

## KMT32B

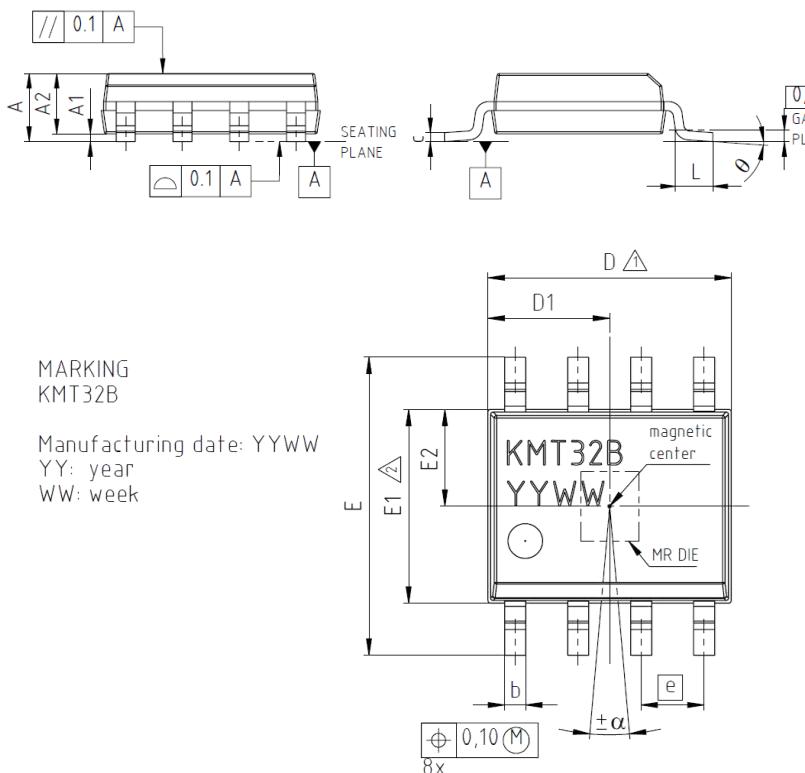
Magnetic Angle Sensor

### Pin Assignment (SO8, TDFN)

Pin (SO8)	Pin (TDFN)	Symbol	Function
1	7	$-V_{o1}$	negative output bridge 1
2	8	$-V_{o2}$	negative output bridge 2
3	1	$V_{cc2}$	positive supply voltage bridge 2
4	2	$V_{cc1}$	positive supply voltage bridge 1
5	3	$+V_{o1}$	positive output bridge 1
6	4	$+V_{o2}$	positive output bridge 2
7	5	$GND_2$	negative supply voltage bridge 2
8	6	$GND_1$	negative supply voltage bridge 1

### Packages

#### SO8



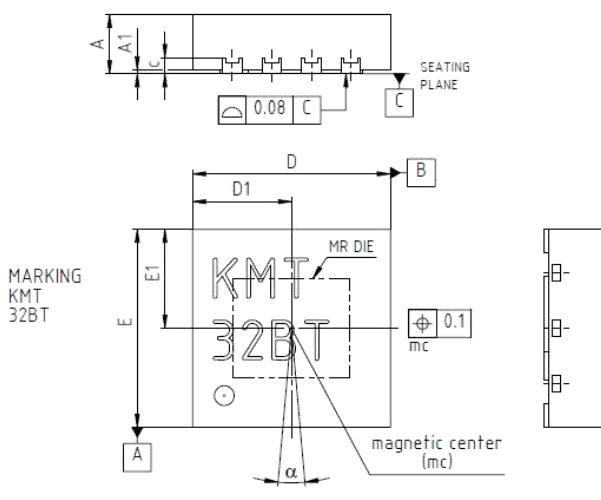
### Quality information

This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q101 - Failure mechanism-based stress test for discrete semiconductor and is suitable for use in automotive applications.

## KMT32B

Magnetic Angle Sensor

**TDFN 2.5 x 2.5 x 0.75 mm<sup>3</sup>**



DIMENSION MM			
REF	MIN.	NOM.	MAX.
A	0.70	0.75	0.80
A1	-	-	0.05
b	0.20	0.25	0.30
c	-	0.20	-
D	2.45	2.50	2.55
D1		1.25	
D2	1.79	1.80	1.81
E	2.45	2.50	2.55
E1	-	1.25	-
E2	1.29	1.30	1.31
e	-	0.50	-
F	-	0.35	-
K	-	0.30	-
L	0.25	0.30	0.35
M	-	0.60	-
N	-	0.35	-
O	-	0.50	-
$\alpha$	-5°	0°	5°

### Quality information

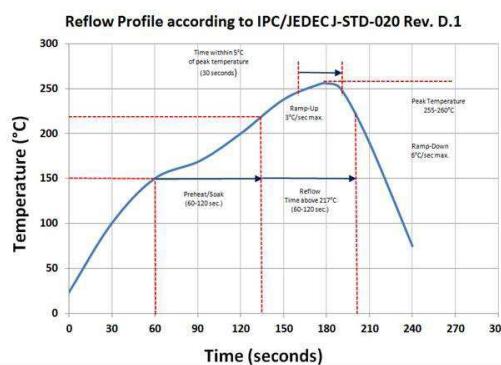
This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q101 - Failure mechanism-based stress test for discrete semiconductor.

### Solder Profile

#### KMT32BT/G-MRCO-016

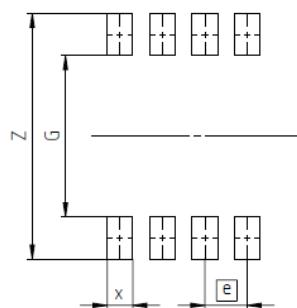
Package: 8L TDFN 2.5 x 2.5

##### Solder Profile



##### Recommended Land Pattern

##### RECOMMENDED LAND PATTERN



DIMENSION MM			
REF	MIN.	NOM.	MAX.
X	-	0.30	-
G	1.90	-	-
Z	-	-	2.90
e	-	0.50	-

Moisture Sensitivity Level for KMT32BT: MSL1 @ 260°C

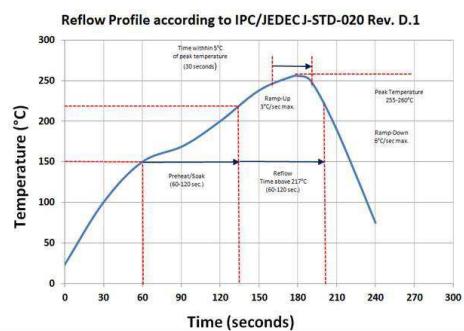
## KMT32B

Magnetic Angle Sensor

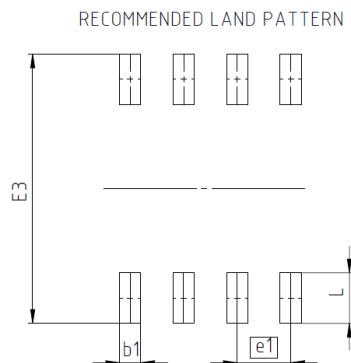
### KMT32B/G-MRCO-015

Package: SO8

#### Solder Profile



#### Recommended Land Pattern



DIM	Millimeter		
	min.	typ.	max.
b1	-	0.50	-
E3	-	6.40	-
e1	-	1.27	-
L	-	1.20	-

Moisture Sensitivity Level for KMT32B: MSL1 @ 260°C

#### Tape and Reel Packaging Information

Description	Part#	Reel size	Units/reel	Pin 1 orientation	Note
KMT32B/TD	G-MRCO-016	7"	3,000	Top-right of sprocket hole side	
KMT32B/SO	G-MRCO-016	13"	2,500	Top-left of sprocket hole side	

## KMT32B

Magnetic Angle Sensor

### Ordering Information

Description	Part Number
KMT32B 8L SOIC ROHS	G-MRCO-015
KMT32BT TDFN ROHS	G-MRCO-016

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