



RoHS

KMT37

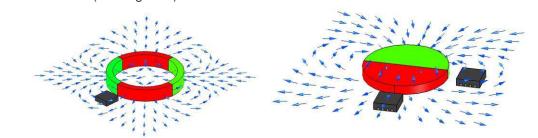
Magnetic Angle Sensor

SPECIFICATIONS

- AMR Sensor with 180° period
- For the use at moderate field strengths
- High accuracy
- Reliable SO8-package
- Qualified for automotive applications

The KMT37 is a magnetic field sensor based on the anisotropic magneto resistance effect, i.e. it is sensing the **magnetic field direction** independently on the magnetic field strength for applied field strengths H>=14 kA/m. The sensor contains two parallel supplied Wheatstone bridges, which enclose a sensitive angle of 45 degrees.

A rotating magnetic field in the surface parallel to the chip (x-y plane) will deliver two independent sinusoidal output signals, one following a $\cos(2\alpha)$ and the second following a $\sin(2\alpha)$ function, α being the angle between sensor and field direction (See Figure 2).



FEATURES

- Contactless angular position
- Design optimized linearity
- High accuracy
- Low cost, low power
- Self diagnosis feature
- User has complete control over signal evaluation
- Reliable SO8-Package
- High rotational speed possible
- Extended operating temperature range
- (-40 °C to +150 °C)
- Ideal for harsh environments due to magnetic sensing principle
- RoHS compliant (lead free)

APPLICATIONS

- Absolute and incremental angle measurement
- Motor motion control
- Robotics
- Camera positioning
- Potentiometer replacement
- Position measurement in medical applications
- Automotive (steering angle, torque, etc.)

CHARACTERISTIC VALUES

Parameter	Condition	Symbol	Min	Тур	Max	Unit
Absolute maximum ratings						
Supply voltage		Vcc			10	V
Operating temperature		Тор	-40		+150	°C
Storage temperature		T _{ST}	-50		+150	°C
Operating conditions						
Supply voltage		V _{CC}	0	5	8.5	V
Applied magnetic field		Н	14	25	400	kA/m

General parameters						
Bridge resistance	T = 25 °C	R _B	2.4	3.0	3.6	kΩ
max. signal amplitude	T = 25 °C, H = 25 kA/m	ΔV/Vcc	9	11	13	mV/V
Offset voltage 2)	T = 25 °C, H = 25 kA/m	V _{OFF} /V _{CC}	-1		+1	mV/V
Hysteresis 1) (Repeatability)	H = 14 kA/m H = 25 kA/m	Hyst		0.1 0.05	0.4 0.1	deg
Accuracy 1)	H = 14 kA/m H = 25 kA/m	Δα		0.1 0.05	0.5 0.15	deg
TC of amplitude	H = 25 kA/m, 3)	TCsv		-0.35		%/K
TC of bridge resistance	3)	TCBR		+0.35		%/K
TC of offset voltage	H = 25 kA/m, 1), 2)	TC _{Voff}	-4	0	+4	μV/V/K
Amplitude synchronism	H = 25 kA/m, 4)	k	99.5	100	100.5	%
Sensitivity (zero crossing)	H = 25 kA/m, 4), $\alpha 1 = 135^{\circ}, \alpha 2 = 0^{\circ}$	Sa1 or Sa2	ΔV _n /V _{cc} [mV/V] x π / 180° r		mV/V/deg	
Peak output voltage	H = 25 kA/m, V _{CC} = 5 V, 4)	V _{po} n	45	55	65	mV/V

- 1) Hysteresis and accuracy are depending nearly inversely proportional on the magnetic field strength. The accuracy is defined as the max. angular difference between actual field angle and measured angle calculated from the third and fifth harmonics of the Fourier spectrum. The hysteresis is defined as angular difference between left and right turn.
- 2) Offset voltages are calculated by measuring both output voltages at several field angles between 0 and 360°, then drawing a diagram with the output voltages as axis and fitting a circle to the signal points. The Offsets are the coordinates of the circle center.
- 3) Reference temperature (Temp. with parameter value = 100%) Tref = -25 °C, calculated from values at -25°C and +125 °C.
- 4) This parameter is given for reference only and is not measured on a regular basis.

BLOCK DIAGRAM

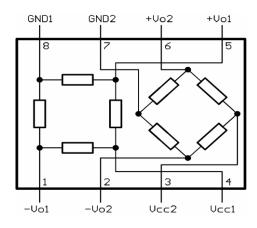


Figure 1: internal and external connections

TYPICAL PERFORMANCE CURVES

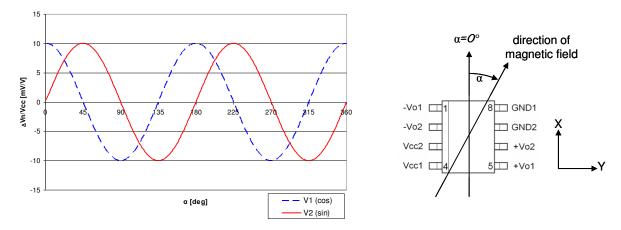
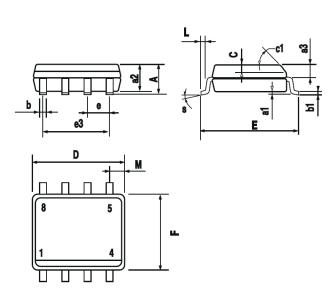


Figure 2: Characteristic curves for KMT37

SENSOR OUTLINE



	mm			inch			
DIM.	MIN.	TYP.	MAX	MIN.	TYP.	MAX	
А			1.75			0.069	
a1	0.1		0.25	0.004		0.010	
a2			1.65			0.065	
a3	0.65		0.85	0.026		0.033	
b	0.35		0.48	0.014		0.019	
b1	0.19		0.25	0.007		0.010	
С	0.25		0.5	0.010		0.020	
c1		45° (typ.)					
D (1)	4.8		5.0	0.189		0.197	
E	5.8		6.2	0.228		0.244	
е		1.27			0.050		
e3		3.81			0.150		
F (1)	3.8		4.0	0.150		0.157	
L	0.4		1.27	0.016		0.050	
М			0.6			0.024	
S	8° (max.)						

Figure 3: SO8-Package

PIN ASSIGNMENT

Pin	Symbol	Function
1	-V _{o1}	negative output bridge 1
2	-V ₀₂	negative output bridge 2
3	V _{cc2}	positive supply voltage bridge 2
4	V _{cc1}	positive supply voltage bridge 1
5	+V ₀₁	positive output bridge 1
6	+V ₀₂	positive output bridge 2
7	GND ₂	negative supply voltage bridge 2
8	GND1	negative supply voltage bridge 1

SOLDER PROFILE

Recommended solder reflow process according to IPC/JEDEC J-STD-020D (Pb-Free Process)

ORDERING CODE

DEVICE	DELIVERY FORM	MOQ	PART NUMBER	
КМТ37	TnR	1 Reel (2500 pcs.)	G-MRCO-037	
КМТ37	Tube	1 Tube	on request	

神州融安科技 (北京)有限公司

电话:010-62127688、82057633

地址:北京市海淀区花园路2号牡丹科技楼B座三层B308室

网址: www. ronganchi na. cn

NORTH AMERICA

TE Connectivity Sensors, Inc. 1000 Lucas Way Hampton, VA 23666 United States

Phone: +1-800-745-8008 Fax: +1-757-766-4297 Email: customercare.hmpt@te.com Web: www.te.com

EUROPE

TE Connectivity Sensors Germany GmbH Hauert 13 D-44227 Dortmund Germany Phone: +49-(0)231-9740-0 Fax: +49-(0)231-9740-200 Email: customercare.dtmd@te.com Web: www.te.com

www.te.com

TE Connectivity, TE Connectivity (logo) and EVERY CONNECTION COUNTS are trademarks. All other logos, products and/or company names referred to herein might be trademarks of their respective owners.

The information given herein, including drawings, illustrations and schematics which are intended for illustration purposes only, is believed to be reliable. However, TE Connectivity makes no warranties as to its accuracy or completeness and disclaims any liability in connection with its use. TE Connectivity's obligations shall only be as set forth in TE Connectivity's Standard Terms and Conditions of Sale for this product and in no case will TE Connectivity be liable for any incidental, indirect or consequential damages arising out of the sale, resale, use or misuse of the product. Users of TE Connectivity products should make their own evaluation to determine the suitability of each such product for the specific application.

© 2020 TE Connectivity Ltd. family of companies All Rights Reserved.